



Tire Rolling and Slipping Formulas

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List of 17 Tire Rolling and Slipping Formulas







5) Roll rate or Roll stiffness
$$\checkmark$$

($K_{\Phi} = \frac{(a^2) \cdot K_t}{2}$
($K_{\Phi} = \frac{(a^2) \cdot K_t}{2}$
($R_{\Phi} = \frac{((1.2m)^2) \cdot 100N/m}{2}$
6) Rolling Radius of Tire \checkmark
($R_w = \frac{2}{3} \cdot R_g + \frac{1}{3} \cdot R_h$
($R_w = \frac{2}{3} \cdot R_g + \frac{1}{3} \cdot R_h$
($R_w = \frac{2}{3} \cdot 0.45m + \frac{1}{3} \cdot 0.35m$
7) Rolling Resistance at Wheels \checkmark
($R_w = \frac{1}{3} \cdot 0.45m + \frac{1}{3} \cdot 0.35m$
7) Rolling Resistance at Wheels \checkmark
($R_w = \frac{1}{3} \cdot 0.45m + \frac{1}{3} \cdot 0.35m$
7) Rolling Resistance Coefficient \checkmark
8) Rolling Resistance Coefficient \checkmark
($R_w = \frac{1}{2}$
($R_$











12) Slip Ratio Defined According to SAE J670 🕑

$$\label{eq:SR} \begin{split} & \textbf{K} = \Omega_w \cdot \frac{R_e}{V_{Roadway} \cdot \cos\left(\alpha_{slip}\right)} - 1 \end{split} \qquad \textbf{Open Calculator Constraints} \\ & \textbf{Open Ca$$

13) Slip Ratio given Longitudinal Slip Velocity and Velocity of Free Rolling Wheel

fx
$$\mathrm{SR}=rac{\mathrm{S}_{\mathrm{ltd}}}{\Omega_0}$$
 ex $0.181818=rac{\mathrm{9rad/s}}{\mathrm{49.5rad/s}}$

14) Slip Ratio given Velocity of Driven Wheel and Free Rolling Wheel



Open Calculator

16) Tractive Effort in Multi-Geared Vehicle at any given Gear 子

$$\mathbf{F}_{t} = \frac{T_{p} \cdot \mathbf{i}_{g} \cdot \mathbf{i}_{o} \cdot \eta_{t}}{\mathbf{r}_{d}}$$

$$\mathbf{F}_{t} = \frac{T_{p} \cdot \mathbf{i}_{g} \cdot \mathbf{i}_{o} \cdot \eta_{t}}{\mathbf{r}_{d}}$$

$$\mathbf{ex} 2078.018N = \frac{270N^{*}m \cdot 2.55 \cdot 2 \cdot 0.83}{0.55m}$$

$$\mathbf{17}$$
Wheel rate given Roll rate

fx
$$K_t = \frac{2 \cdot K_{\Phi}}{a^2}$$

ex $100 \text{N/m} = \frac{2 \cdot 72 \text{Nm/rad}}{(1.2 \text{m})^2}$





Variables Used

- **a** Track Width of Vehicle (Meter)
- **a_v** Distance of Opposing Torque from Vertical (*Meter*)
- **F**_a Gradient Resistance (Newton)
- **f**_r Rolling Resistance Coefficient
- **F**_r Rolling Resistance at Wheel (*Newton*)
- **F**_t Tractive Effort in Multi-geared Vehicle (Newton)
- g Acceleration due to Gravity (Meter per Square Second)
- G Weight on Single Wheel (Newton)
- **i**_q Gear Ratio of Transmission
- **i**o Gear Ratio of Final Drive
- Kt Wheel Rate of Vehicle (Newton per Meter)
- Ko Roll Rate/ Roll Stiffness (Newton Meter per Radian)
- **M**_v Vehicle Weight in Newtons (Newton)
- P Normal Load on Wheels (Newton)
- r Effective Wheel Radius (Meter)
- R Traction Force required to Climb Curb (Newton)
- rd Effective Radius of Wheel (Meter)
- Re Effective Rolling Radius for Free Rolling (Meter)
- R_q Geometrical Radius of Tire (Meter)
- R_h Loaded Height of Tire (Meter)
- RI Height of Axle above Road Surface (Loaded Radius) (Meter)

- **R**_w Rolling Radius of Tire (*Meter*)
- Sltd Longitudinal Slip Angular Velocity (Radian per Second)
- SR Slip Ratio
- **T**_p Torque Output of Vehicle (Newton Meter)
- **V** Forward Velocity of Vehicle (*Meter per Second*)
- **V**_B Circumferential Velocity of Tire under Traction (*Meter per Second*)
- Vlateral Lateral Slip Velocity (Meter per Second)
- Vlongitudinal Longitudinal Slip Velocity (Meter per Second)
- VRoadway Axle Speed over Roadway (Meter per Second)
- α Angle of Inclination of Ground from Horizontal (Radian)
- α_{slip} Slip Angle (Radian)
- η_t Transmission Efficiency of Vehicle
- **θ** Angle between Traction Force and Horizontal Axis (*Radian*)
- λ Slip of Tire
- ω Vehicle Wheel Angular Velocity (Radian per Second)
- Ω Angular Velocity of Driven or Braked Wheel (Radian per Second)
- Ω₀ Angular Velocity of Free Rolling Wheel (Radian per Second)
- Ω_w Wheel Angular Velocity (Radian per Second)



8/10



Constants, Functions, Measurements used

- Function: **cos**, cos(Angle) Cosine of an angle is the ratio of the side adjacent to the angle to the hypotenuse of the triangle.
- Function: sin, sin(Angle) Sine is a trigonometric function that describes the ratio of the length of the opposite side of a right triangle to the length of the hypotenuse.
- Measurement: Length in Meter (m) Length Unit Conversion
- Measurement: Speed in Meter per Second (m/s) Speed Unit Conversion
- Measurement: Acceleration in Meter per Square Second (m/s²) Acceleration Unit Conversion
- Measurement: Force in Newton (N) Force Unit Conversion
- Measurement: Angle in Radian (rad) Angle Unit Conversion
- Measurement: Surface Tension in Newton per Meter (N/m) Surface Tension Unit Conversion
- Measurement: Angular Velocity in Radian per Second (rad/s) Angular Velocity Unit Conversion
- Measurement: Torque in Newton Meter (N*m)
 Torque Unit Conversion
- Measurement: Torsion Constant in Newton Meter per Radian (Nm/rad) Torsion Constant Unit Conversion



Check other formula lists

- Angular Velocity Formulas C
- Wheel Parameters Formulas C
- Tire Rolling and Slipping
 Formulas

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