



Motion in Bodies Hanging by String Formulas

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List of 15 Motion in Bodies Hanging by String Formulas

Motion in Bodies Hanging by String C

Body Lying on Rough Horizontal Plane 🕑

1) Acceleration of System with Bodies One Hanging Free and Other Lying on Rough Horizontal Plane

fx
$$\mathbf{a}_{\mathrm{s}} = rac{\mathrm{m}_1 - \mathrm{\mu}_{\mathrm{hs}} \cdot \mathrm{m}_2}{\mathrm{m}_1 + \mathrm{m}_2} \cdot [\mathrm{g}]$$

ex
$$5.940081 \mathrm{m/s^2} = rac{29 \mathrm{kg} - 0.24 \cdot 13.52 \mathrm{kg}}{29 \mathrm{kg} + 13.52 \mathrm{kg}} \cdot \mathrm{[g]}$$

2) Tension in String given Coefficient of Friction of Horizontal Plane

fx
$$\mathbf{T}_{\mathrm{st}} = (1+\mu_{\mathrm{hor}}) \cdot rac{\mathbf{m}_1 \cdot \mathbf{m}_2}{\mathbf{m}_1 + \mathbf{m}_2} \cdot [\mathbf{g}]$$

ex
$$130.0352$$
N = $(1 + 0.438) \cdot \frac{29$ kg $\cdot 13.52$ kg $\cdot [g]$
 29 kg $+ 13.52$ kg $\cdot [g]$

Open Calculator

Open Calculator

Body Lying on Rough Inclined Plane 🕑

3) Acceleration of System with Bodies One Hanging Free, Other Lying on Rough Inclined Plane

$$\begin{aligned} \mathbf{\widehat{x}} & \mathbf{a}_{i} = \frac{\mathbf{m}_{1} - \mathbf{m}_{2} \cdot \sin\left(\theta_{p}\right) - \mu_{hs} \cdot \mathbf{m}_{2} \cdot \cos\left(\theta_{p}\right)}{\mathbf{m}_{1} + \mathbf{m}_{2}} \cdot [\mathbf{g}] \end{aligned}$$
 Open Calculator (*)

$$\begin{aligned} \mathbf{\widehat{x}} & \mathbf{a}_{i} = \frac{\mathbf{m}_{1} - \mathbf{m}_{2} \cdot \sin\left(13.23^{\circ}\right) - 0.24 \cdot 13.52 \mathrm{kg} \cdot \cos\left(13.23^{\circ}\right)}{29 \mathrm{kg} + 13.52 \mathrm{kg}} \cdot [\mathbf{g}] \end{aligned}$$

$$\begin{aligned} \mathbf{\widehat{x}} & \mathbf{\widehat{x}} & \mathbf{\widehat{x}} \\ \mathbf{\widehat{x}} & \mathbf{\widehat{\mu}}_{hs} = \frac{\mathbf{F}_{fri}}{\mathbf{m}_{2} \cdot [\mathbf{g}] \cdot \cos\left(\theta_{p}\right)} \end{aligned}$$
 Open Calculator (*)

$$\begin{aligned} \mathbf{\widehat{x}} & \mu_{hs} = \frac{\mathbf{F}_{fri}}{\mathbf{m}_{2} \cdot [\mathbf{g}] \cdot \cos\left(\theta_{p}\right)} \end{aligned}$$

$$\begin{aligned} \mathbf{\widehat{x}} & \mathbf{\widehat{x}} \\ \mathbf{\widehat{x}} \\ \mathbf{\widehat{x}} & \mathbf{\widehat{x}} \\ \mathbf{\widehat{x}} \\$$



6) Frictional Force
$$\mathbf{C}$$

(a) $F_{fri} = \mu_{hs} \cdot m_2 \cdot [g] \cdot \cos(\theta_p)$ Open Calculator (*)
(c) $30.97607N = 0.24 \cdot 13.52kg \cdot [g] \cdot \cos(13.23^{\circ})$
7) Inclination of Plane for given Frictional Force (*)
(a) $\theta_p = a \cos\left(\frac{F_{fri}}{\mu_{hs} \cdot m_2 \cdot [g]}\right)$ Open Calculator (*)
(b) $\theta_p = a \cos\left(\frac{30.97607N}{0.24 \cdot 13.52kg \cdot [g]}\right)$
8) Mass of Body B given Frictional Force (*)
(a) $m_2 = \frac{F_{fri}}{\mu_{hs} \cdot [g] \cdot \cos(\theta_p)}$ Open Calculator (*)
(b) $m_2 = \frac{F_{fri}}{\mu_{hs} \cdot [g] \cdot \cos(\theta_p)}$
(c) $m_2 = \frac{30.97607N}{0.24 \cdot [g] \cdot \cos(13.23^{\circ})}$
9) Tension in String given Coefficient of Friction of Inclined Plane (*)
(b) $T_{st} = \frac{m_1 \cdot m_2}{m_1 + m_2} \cdot [g] \cdot (1 + \sin(\theta_p) + \mu_{hs} \cdot \cos(\theta_p))$ Open Calculator (*)
(*) $13.22499N = \frac{29kg \cdot 13.52kg}{29kg + 13.52kg} \cdot [g] \cdot (1 + \sin(13.23^{\circ}) + 0.24 \cdot \cos(13.23^{\circ}))$



()

Body Lying on Smooth Horizontal Plane 🕑

10) Acceleration in System 🕑

$$\begin{aligned} & \mathbf{\hat{fx}} \ \mathbf{\hat{a}_b} = \frac{m_1}{m_1 + m_2} \cdot [\mathbf{g}] \\ & \mathbf{ex} \ 6.688449 \mathrm{m/s^2} = \frac{29 \mathrm{kg}}{29 \mathrm{kg} + 13.52 \mathrm{kg}} \cdot [\mathbf{g}] \\ & \mathbf{11) Tension in String if only One Body is Freely Suspended } \\ & \mathbf{\hat{fx}} \ \mathbf{T}_{\mathrm{fs}} = \frac{m_1 \cdot m_2}{m_1 + m_2} \cdot [\mathbf{g}] \end{aligned}$$

ex
$$90.42783 \mathrm{N} = rac{29 \mathrm{kg} \cdot 13.52 \mathrm{kg}}{29 \mathrm{kg} + 13.52 \mathrm{kg}} \cdot \mathrm{[g]}$$

Body Lying on Smooth Inclined Plane C

12) Acceleration of System with Bodies One Hanging Free and Other Lying on Smooth Inclined Plane





13) Angle of Inclination given Acceleration \mathbf{C} $\theta_{p} = a \sin\left(\frac{m_{1} \cdot [g] - m_{1} \cdot a_{s} - m_{2} \cdot a_{s}}{m_{2} \cdot [g]}\right)$

ex
$$13.88807^{\circ} = a \sin\left(\frac{29 \text{kg} \cdot [\text{g}] - 29 \text{kg} \cdot 5.94 \text{m/s}^2 - 13.52 \text{kg} \cdot 5.94 \text{m/s}^2}{13.52 \text{kg} \cdot [\text{g}]}
ight)$$

14) Angle of Inclination given Tension

$$\mathbf{fx} \theta_{p} = a \sin\left(\frac{T \cdot (m_{1} + m_{2})}{m_{1} \cdot m_{2} \cdot [g]} - 1\right)$$

ex $13.23^{\circ} = a \sin\left(\frac{111.1232N \cdot (29kg + 13.52kg)}{29kg \cdot 13.52kg \cdot [g]} - 1\right)$

15) Tension in String when One Body is Lying on Smooth Inclined Plane

fx
$$T = rac{\mathrm{m_1} \cdot \mathrm{m_2}}{\mathrm{m_1} + \mathrm{m_2}} \cdot [\mathrm{g}] \cdot \left(1 + \mathrm{sin}(\theta_\mathrm{p})\right)$$

ex
$$111.1232N = rac{29 \mathrm{kg} \cdot 13.52 \mathrm{kg}}{29 \mathrm{kg} + 13.52 \mathrm{kg}} \cdot \mathrm{[g]} \cdot (1 + \mathrm{sin}(13.23^\circ))$$

Open Calculator

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Variables Used

- **a**b Acceleration of System (Meter per Square Second)
- **a_i** Acceleration of System in Inclined Plane (Meter per Square Second)
- **a_s** Acceleration of Body (Meter per Square Second)
- F_{fri} Force of Friction (Newton)
- **m₁** Mass of Left Body (*Kilogram*)
- m₂ Mass of Right Body (Kilogram)
- **T** Tension (Newton)
- T_{fs} Tension in Freely Suspended String (Newton)
- T_{st} Tension in String (Newton)
- θ_b Inclination of body (Degree)
- θ_p Inclination of Plane (Degree)
- µhor Coefficient of Friction for Horizontal Plane
- µhs Coefficient of Friction for Hanging String





Constants, Functions, Measurements used

- Constant: [g], 9.80665 Gravitational acceleration on Earth
- Function: acos, acos(Number) The inverse cosine function, is the inverse function of the cosine function. It is the function that takes a ratio as an input and returns the angle whose cosine is equal to that ratio.
- Function: **asin**, asin(Number) The inverse sine function, is a trigonometric function that takes a ratio of two sides of a right triangle and outputs the angle opposite the side with the given ratio.
- Function: **cos**, cos(Angle) Cosine of an angle is the ratio of the side adjacent to the angle to the hypotenuse of the triangle.
- Function: sec, sec(Angle) Secant is a trigonometric function that is defined ratio of the hypotenuse to the shorter side adjacent to an acute angle (in a right-angled triangle); the reciprocal of a cosine.
- Function: **sin**, sin(Angle) Sine is a trigonometric function that describes the ratio of the length of the opposite side of a right triangle to the length of the hypotenuse.
- Function: tan, tan(Angle) The tangent of an angle is a trigonometric ratio of the length of the side opposite an angle to the length of the side adjacent to an angle in a right triangle.
- Measurement: Weight in Kilogram (kg) Weight Unit Conversion
- Measurement: Acceleration in Meter per Square Second (m/s²) Acceleration Unit Conversion
- Measurement: Force in Newton (N) Force Unit Conversion
- Measurement: Angle in Degree (°) Angle Unit Conversion



Check other formula lists

Motion in Bodies Hanging by String
 Projectile Motion Formulas
 Formulas

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